**Department of Computer Science** National Tsing Hua University

# CS 5244: Introduction to Cyber Physical Systems

#### **Unit 5: Memory Architectures (Ch. 8)**

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Acknowledgement: The instructor thanks Profs. Edward A. Lee & Sanjit A. Seshia at UC Berkeley for sharing their course materials

# Memory Architecture: Issues

- o Types of memory
- o Stack
- o Caches
- o Scratchpad memories
- o Absolute and relative addresses
- o Virtual memory
- o Heaps

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- allocation/deallocation
- fragmentation
- garbage collection
- o Segmented memory spaces

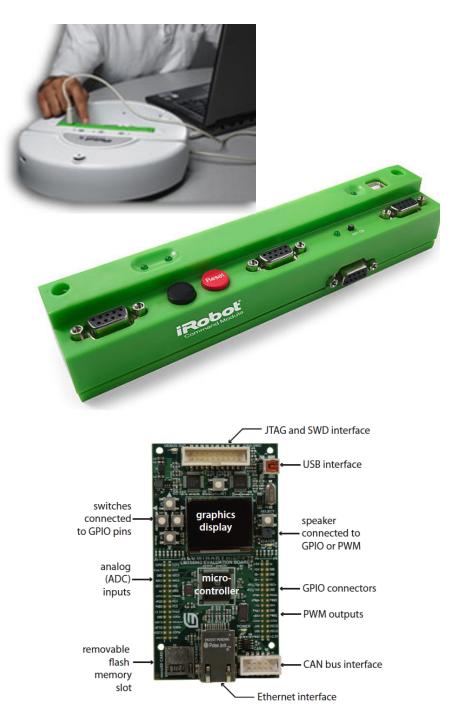
These issues loom larger in embedded systems than in general-purpose computing.

### **Specific Examples**

To be concrete:

A low-end example:
 8-bit microcomputer

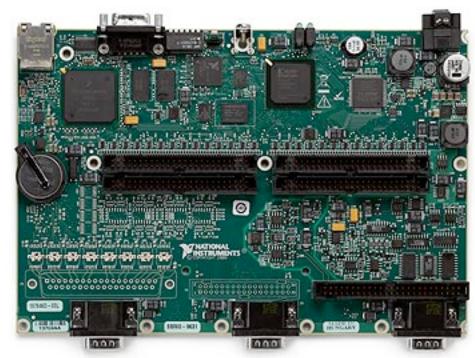
• A medium-end example: 32-bit microcomputer



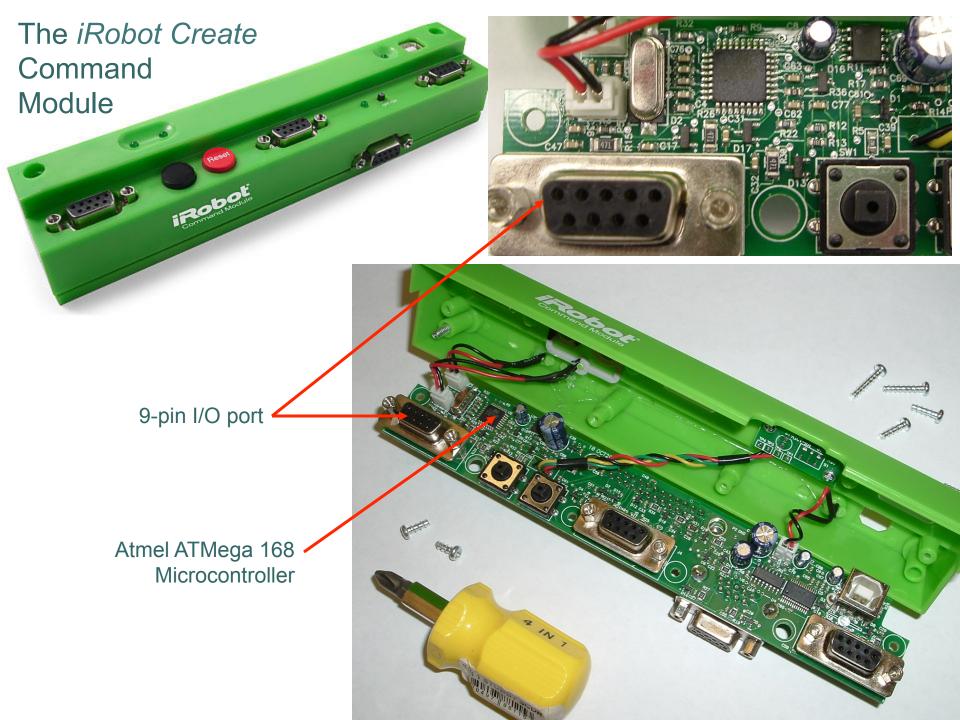
Specific Examples (Continued)

Single-Board RIO (National Instruments)

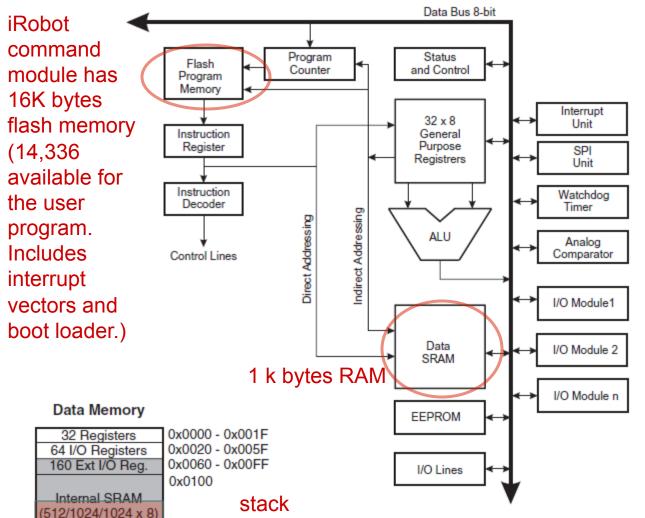
- Xilinx FPGA
  - In our lab: preconfigured with a 32-bit MicroBlaze microprocessor running without an operating system ("bare iron").



- PowerPC processor (Freescale MPC5200)
  - In our lab: running VxWorks RTOS (real-time operating system) or LabVIEW Embedded.



## ATMega168 Memory Architecture An 8-bit microcontroller with 16-bit addresses

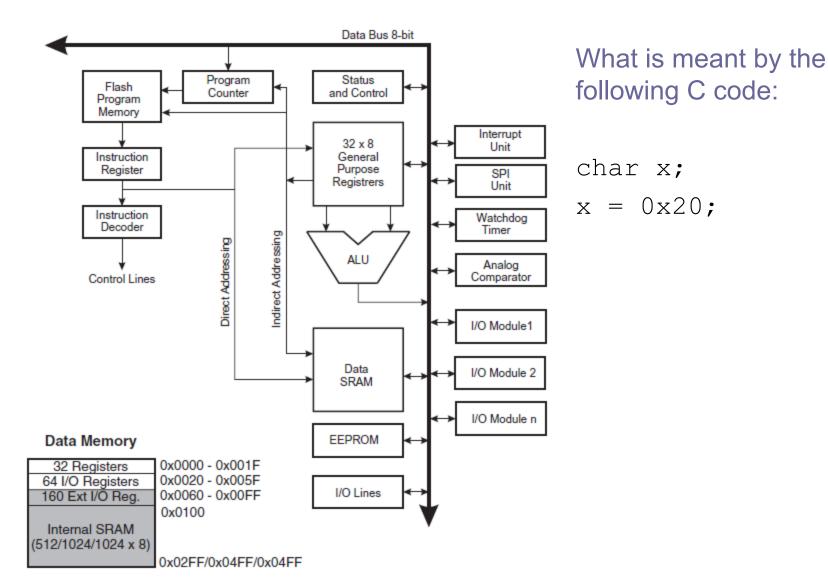


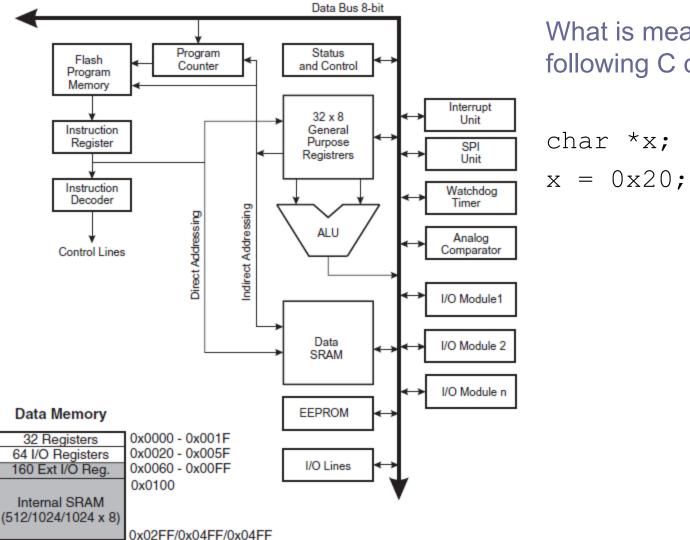
0x02FF/0x04FF/0x04FF

Example of a microcontroller architecture. Used in iRobot command module.

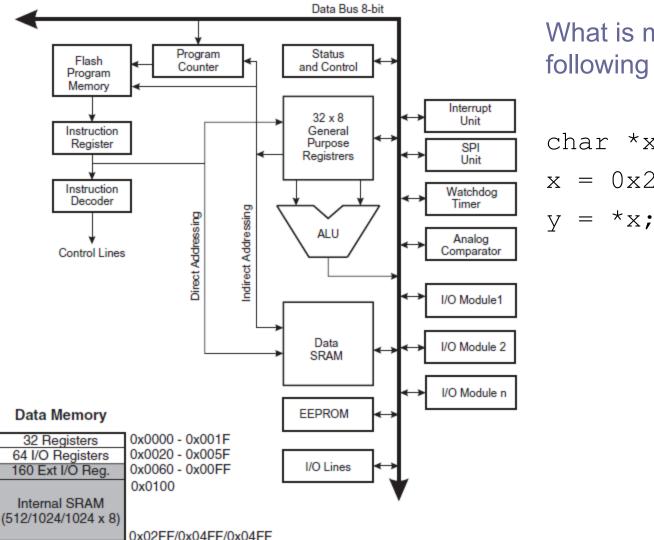
Additional I/O on the command module: •Two 8-bit timer/counters •One 16-bit timer/counter •6 PWM channels •8-channel, 10-bit ADC •One serial UART •2-wire serial interface

Source: ATmega168 Reference Manual



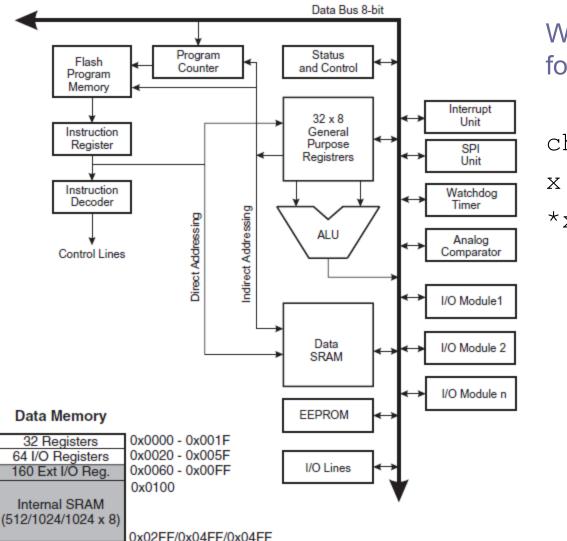


What is meant by the following C code:



What is meant by the following C code:

char \*x, y; x = 0x20;

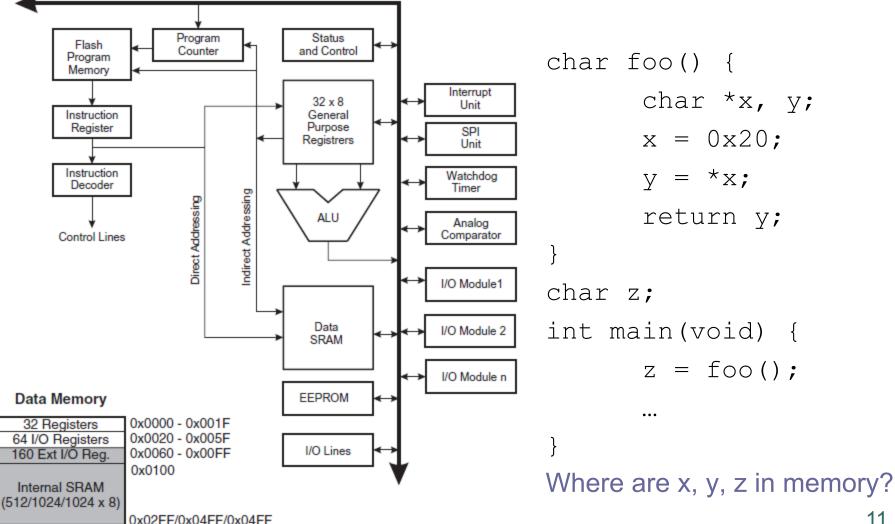


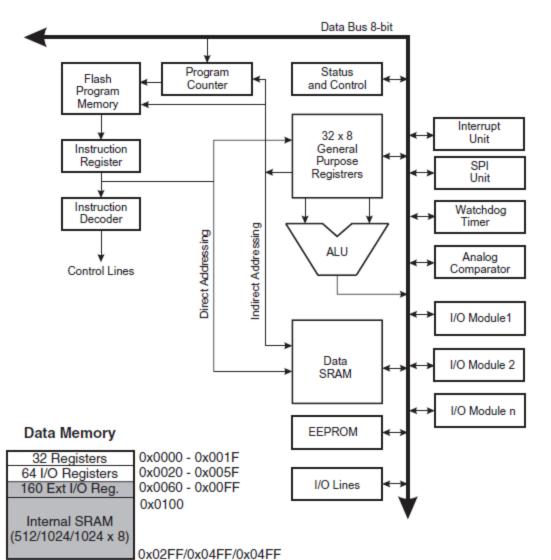
What is meant by the following C code:

char \*x, y; x = &y; \*x = 0x20;

Data Bus 8-bit

What is meant by the following C code:



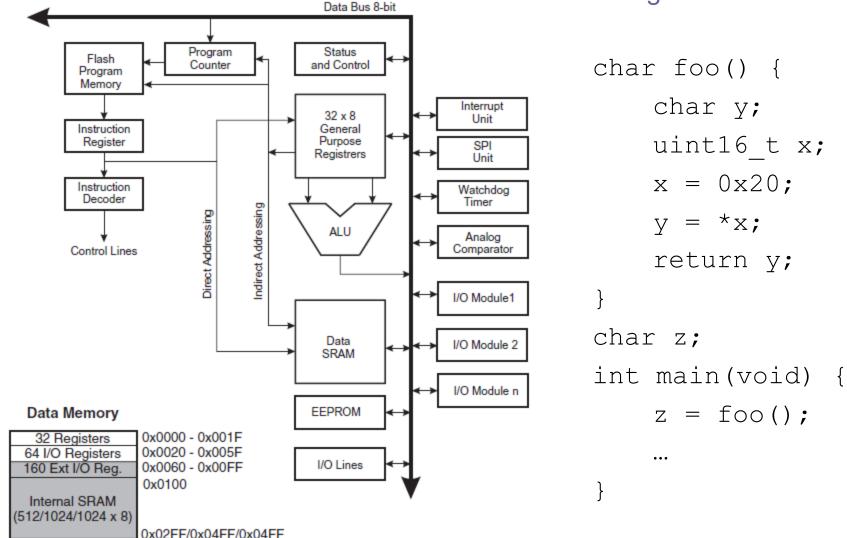


```
char foo() {
    char *x, y;
    x = 0x20;
    y = *x;
    return y;
}
char z;
int main(void) {
    z = foo();
```

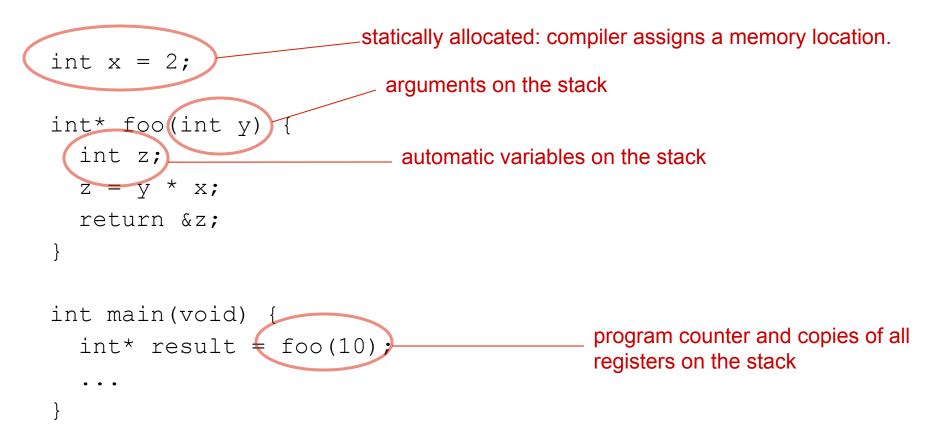
x occupies 2 bytes on the stack, y occupies 1 byte on the stack, and z occupies 1 byte in static memory.

. . .

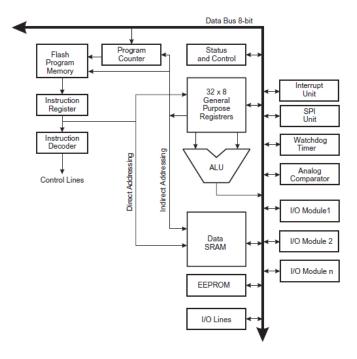
What is meant by the following C code:



#### Memory usage: Understanding the stack. Find the flaw in this program



This program returns a pointer to a variable on the stack. What if another procedure call occurs before the returned pointer is de-referenced?



void foo(uint16 t x) char y; y = \*x;if (x > 0x100) { foo(x - 1);char z; void main(...) {  $z = 0 \times 10;$ foo(0x04FF);

What is the value of z?

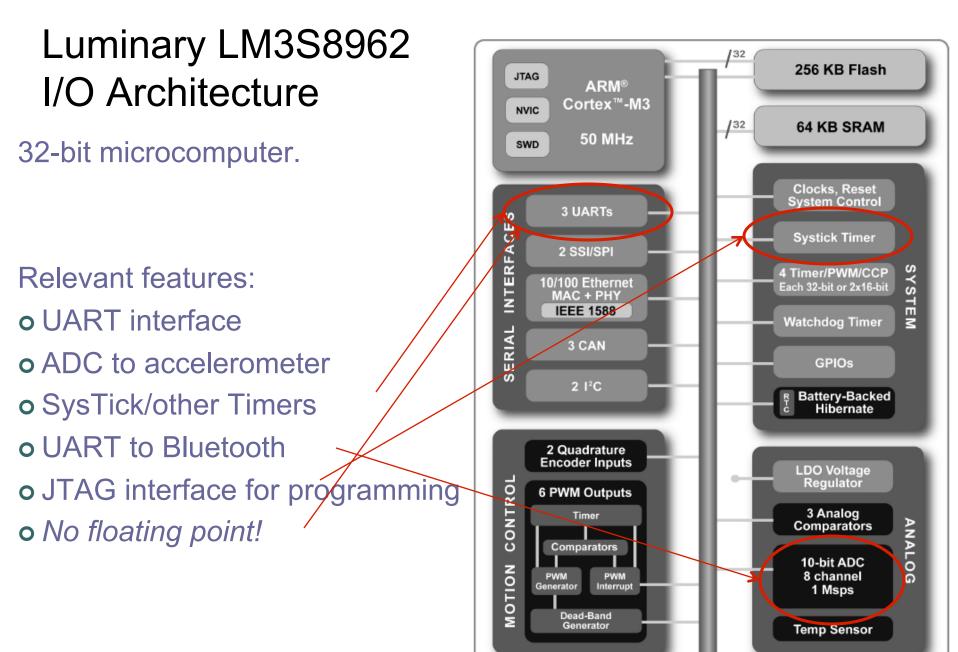
...

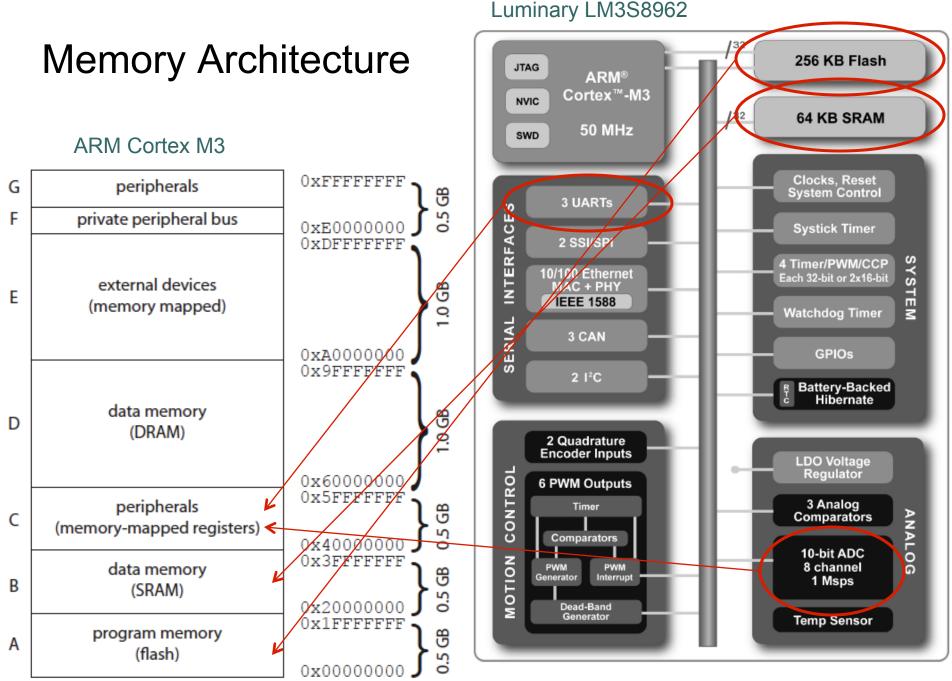
#### **Data Memory**

32 Registers	0x0000 - 0x001F
64 I/O Registers	0x0020 - 0x005F
160 Ext I/O Reg.	0x0060 - 0x00FF
	0x0100
Internal SRAM	
(512/1024/1024 x 8)	
(/	0x02FF/0x04FF/0x04FF



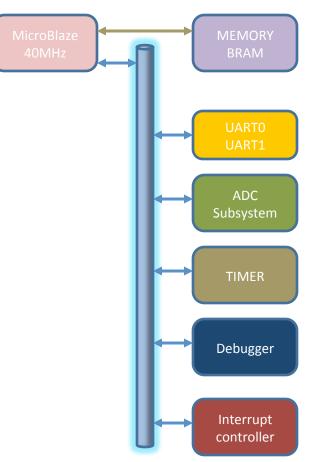
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#### Source: Luminary Micro Datasheet

#### Microblaze memory map Xilinx soft core



	0xFFFFFFFF
Unmapped Area	
	0x8440FFFF
Debugger	
Unmapped Area	0x84400000 0x8402FFFF
UARTs	
Unmapped Area	0x84000000
	0x83C0FFFF
Timer	0x83C00000
Unmapped Area	0x8180FFFF
Interrupt controller	
Unmapped Area	0x81800000 0x814CFFFF
ADC subsystem	
Unmapped Area	0x81420000
	0x0000FFFF
Memory for	
Instructions and Data	0x00000000

Thanks to Trung Tran

An operating system typically offers a way to dynamically allocate memory on a "heap".

Memory management (malloc() and free()) can lead to many problems with embedded systems:

- Memory leaks (allocated memory is never freed)
- Memory fragmentation (allocatable pieces get smaller)

Automatic techniques ("garbage collection") typically require stopping everything and reorganizing the allocated memory. This is deadly for real-time programs.



Understanding memory architectures is essential to programming embedded systems.